



國立高雄科技大學

National Kaohsiung University of Science and Technology

Region of Interest (RoI)

Pooling and Align

Speaker: Shih-Shinh Huang

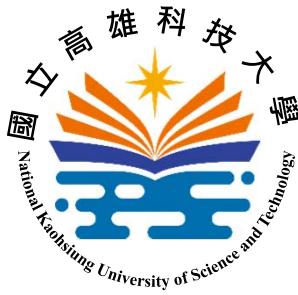
February 21, 2021





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 - Overview
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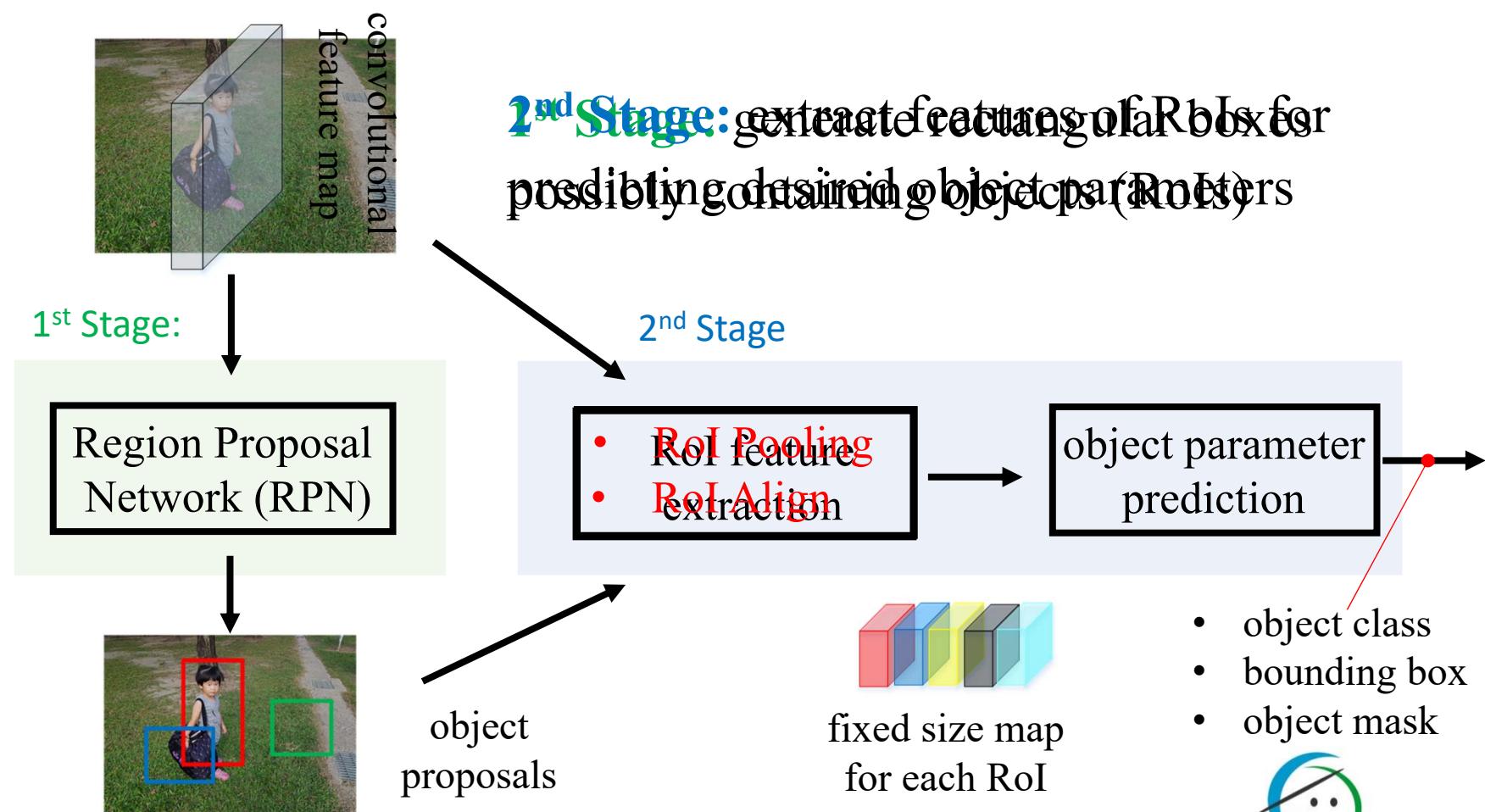
Introduction

- Background
 - Detecting and segmenting objects from images are important tasks in computer vision area.
 - **Faster R-CNN:** well-known method for detection

Shaoqing Ren, *et. al.*, “Faster R-CNN Towards Real-Time Object Detection with Region Proposal Networks,” *IEEE Trans. on PAMI*, 2017.
 - **Mask R-CNN:** well-known method for segmentation

Kaiming He, *et. al.*, “Mask R-CNN,” *IEEE ICCV*, 2017

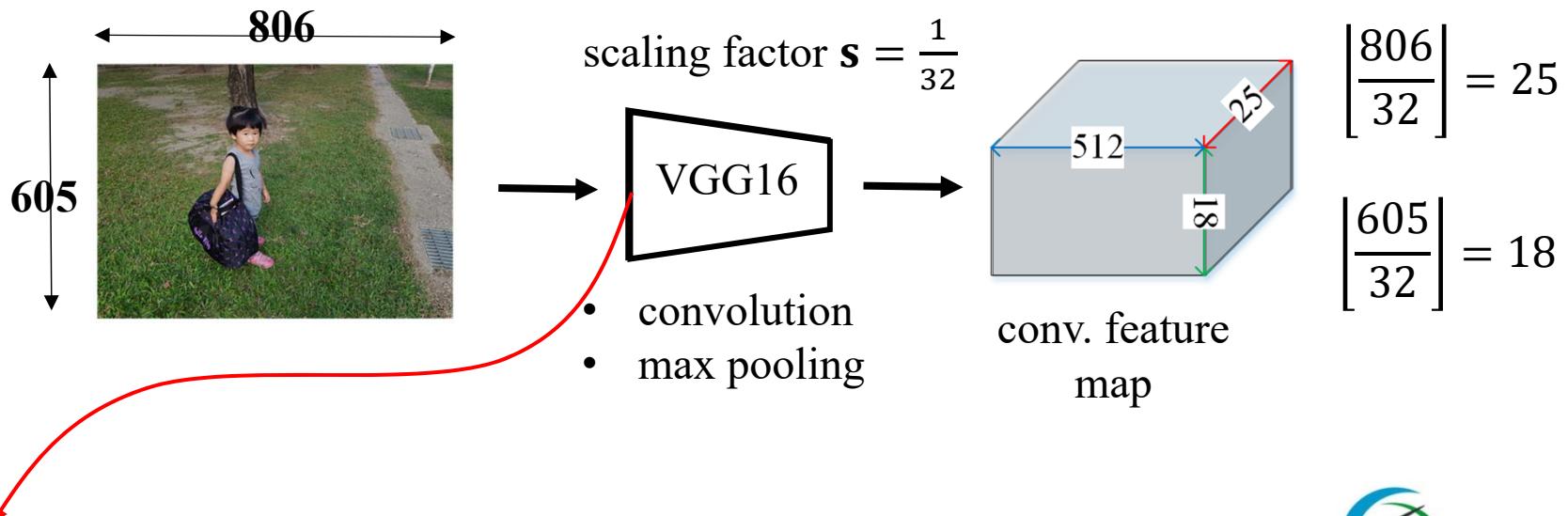
Introduction





Introduction

- ROI Feature Extraction: input
 - Feature Map: feature of the input image obtained from a deep convolutional neural network.

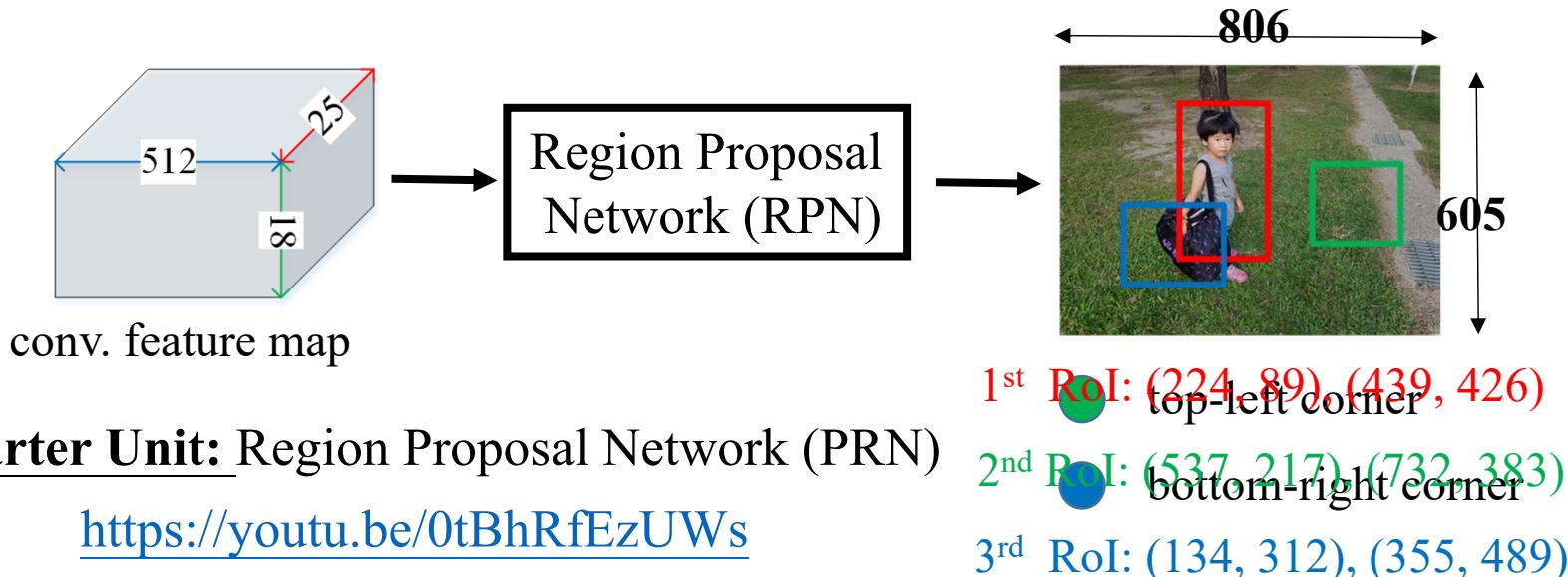


K. Simonyan et. al. “Very Deep Convolutional Networks for Large-Scale Image Recognition,” *ICLR*, 2015.



Introduction

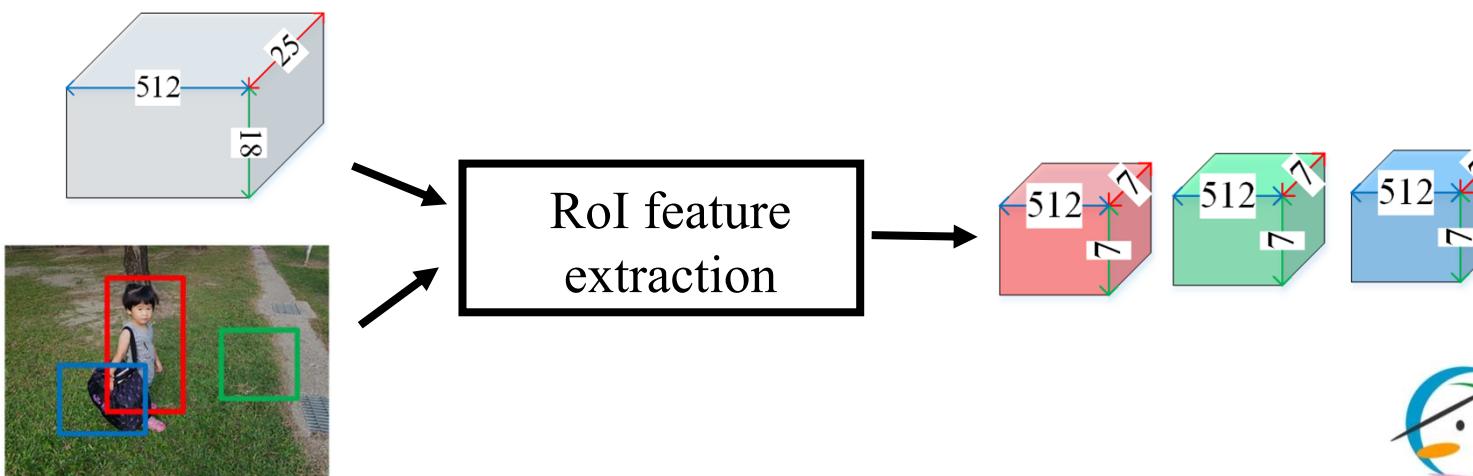
- ROI Feature Extraction: input
 - ROI List: object proposals from RPN

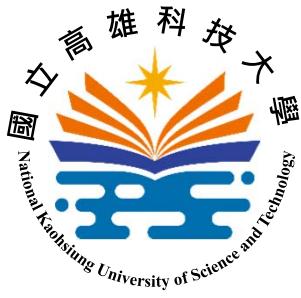


Shaoqing Ren, *et. al.*, “Faster R-CNN Towards Real-Time Object Detection with Region Proposal Networks,” *IEEE Trans. on PAMI*, 2017.

Introduction

- ROI Feature Extraction: output
 - ROI feature maps: each one is the feature map **within** a ROI and with the fixed size $k \times k \times c$
 - k : pre-defined size ($k = 7$ in original paper)
 - c : num. of channels of input conv. feature map





RoI Pooling

- Overview
 - RoI pooling is firstly proposed in Fast R-CNN for object detection.
Ross Girshick, “Fast R-CNN,” *IEEE ICCV*, 2015
 - RoI pooling uses **max pooling** operation for computing the RoI feature map.
 - make the conv. feature map be **reused** for all RoIs
 - make the architecture be trained **end-to-end**.

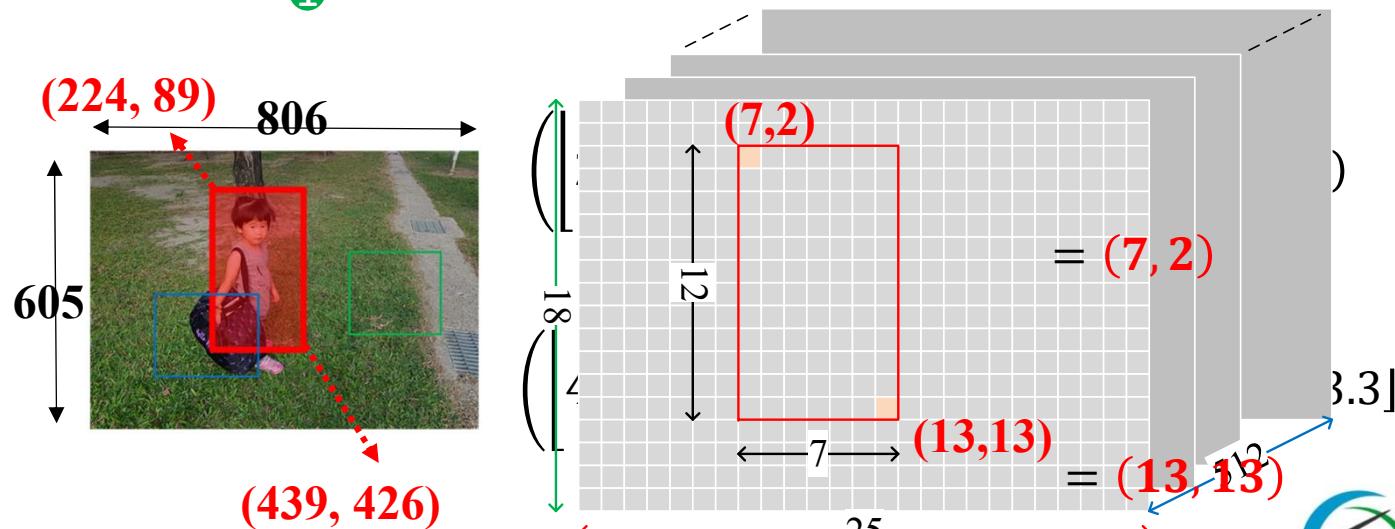


RoI Pooling

- Overview: three steps
 - Step 1 (RoI mapping): map RoI bounding box from image to conv. feature map by quantization
 - Step 2 (RoI division): divide the mapped RoI into $k \times k$ grids by quantization
 - Step 3 (max pooling): find the maximum of all points in a grid

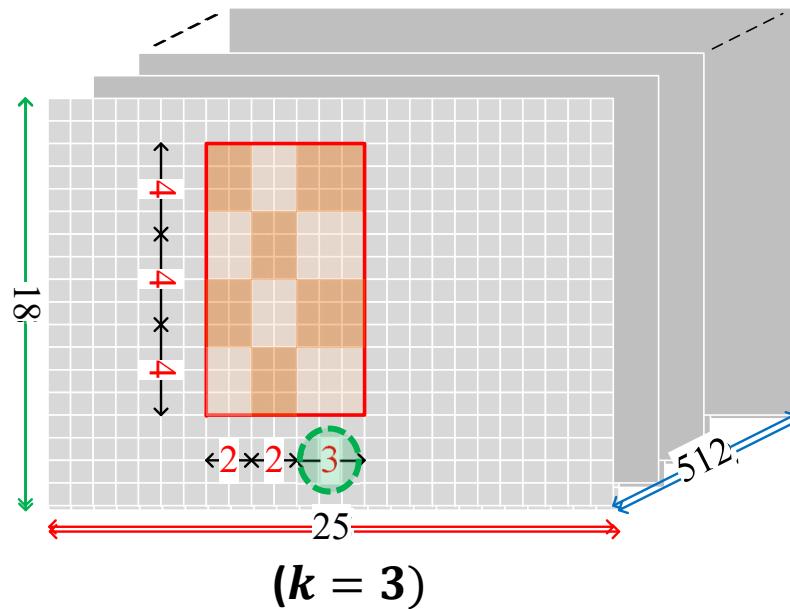
RoI Pooling

- Pooling Steps: RoI mapping
 - multiple the coordinates of RoI corners by the scaling factor s
 - quantize₁ the resulting coordinates by floor operator



RoI Pooling

- Pooling Steps: RoI division
 - divide the width/height of the mapped RoI by k
 - quantize the width/height by floor operator
 $\lfloor \frac{7}{3} \rfloor = \lfloor 2.33 \rfloor = 2$

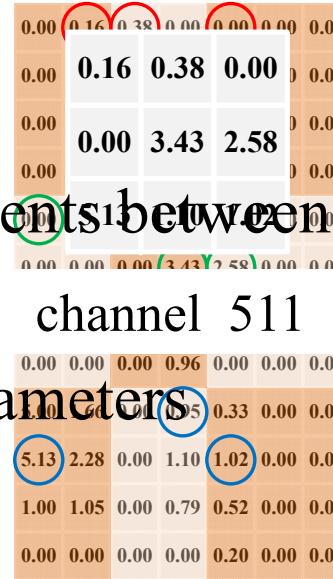


RoI Pooling

- Pooling Steps: max pooling
 - take the maximum of points in each grid
 - aggregate the results in all channels

Disadvantages:

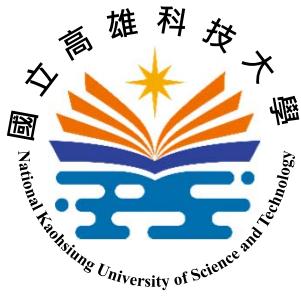
- Using quantization introduces misalignments between the RoI and the extracted feature map.
- This makes predicting pixel-accurate parameters difficult.





RoI Align

- Overview
 - RoI align was proposed and used for instance segmentation in Mask R-CNN.
- Objective: perform data pooling more accurate.
 - perform RoI mapping and division without quantization.
 - interpolate the values of sampling points for data pooling.

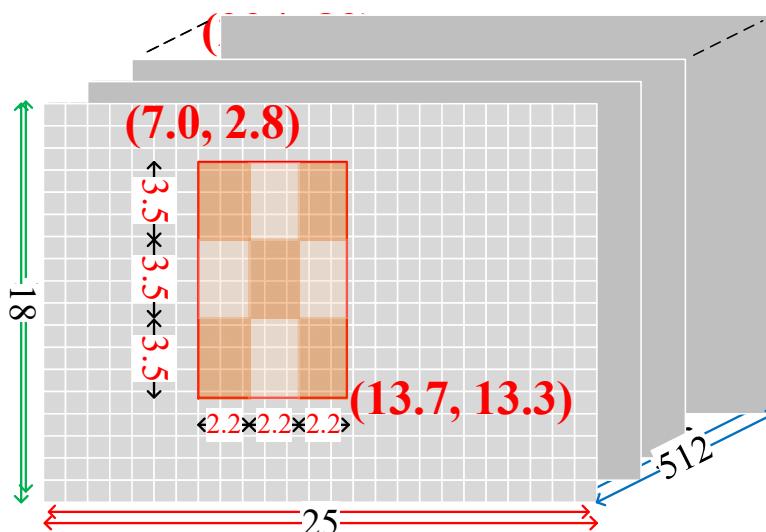


RoI Align

- Overview: four steps
 - Step 1 (RoI mapping): multiply the scaling factor to map RoI to conv. feature map
 - Step 2 (RoI division): divide the width/height of mapped RoI by k to have $k \times k$ grids.
 - Step 3 (Interpolation): interpolate the values of all sampling points (each grid has $s \times s$ points)
 - Step 4 (max pooling): find the maximum of all $s \times s$ sampling points in a grid.

RoI Align

- Align Steps
 - ROI mapping: multiple the scaling factor
 - ROI division: divide width/height by k



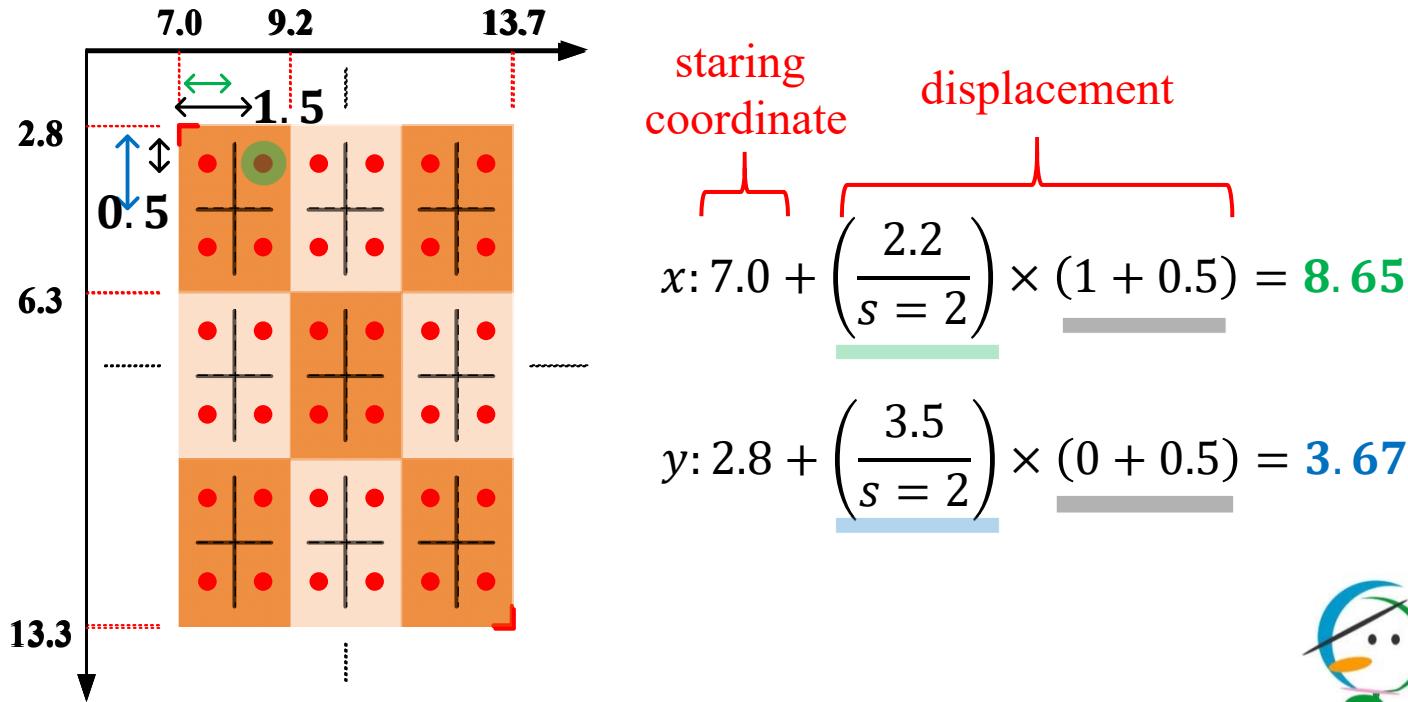
$$\left(\left\lfloor \frac{7.0 + 3}{32} \right\rfloor, \left\lfloor \frac{2.8 + 3}{32} \right\rfloor \right) = (7.0, 2.8)$$

grid width: $6.7 \div 3 = 2.2$

$$\left(\left\lfloor \frac{\text{grid height}}{32} \right\rfloor, \left\lfloor \frac{13.7 + 3}{32} \right\rfloor \right) = (13.7, 13.3)$$

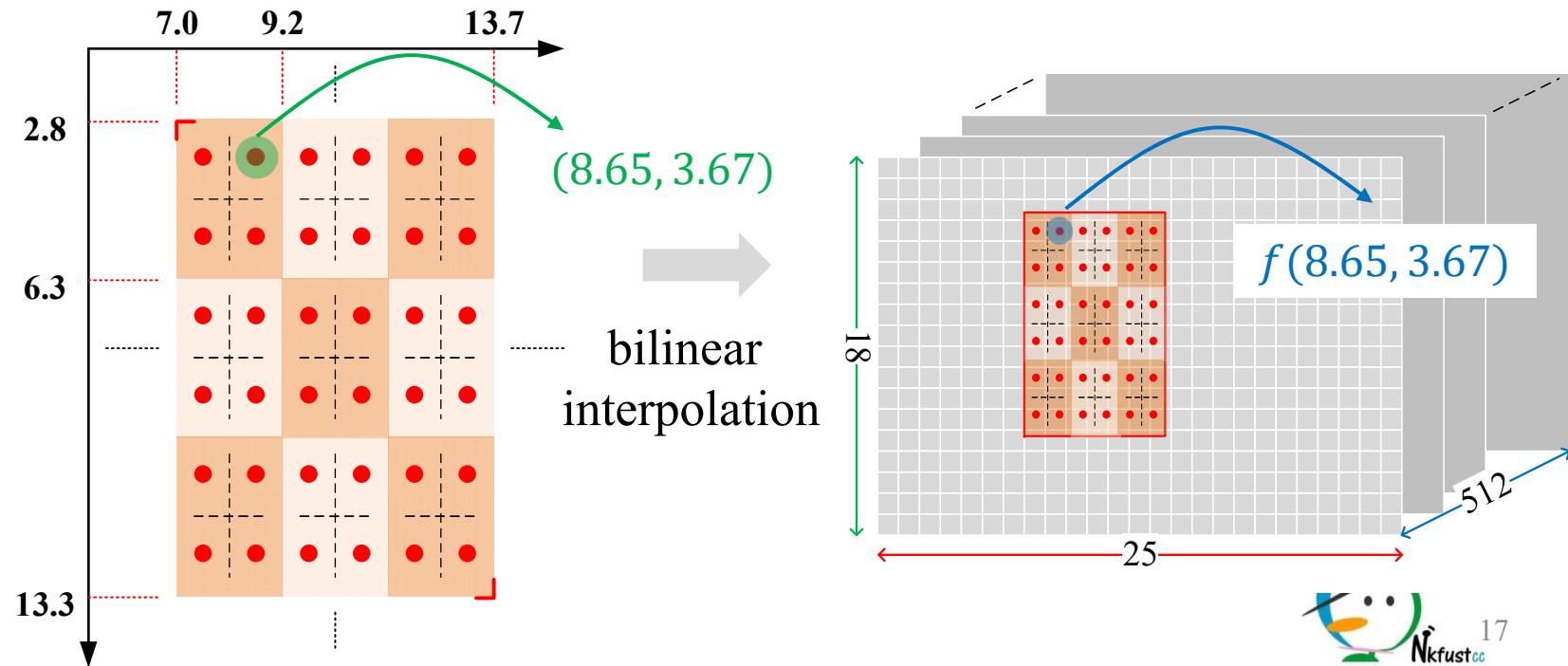
RoI Align

- Align Steps: interpolation
 - divide each grid into $s \times s$ cells ($s = 2$)
 - take the centroids of cells as sampling points



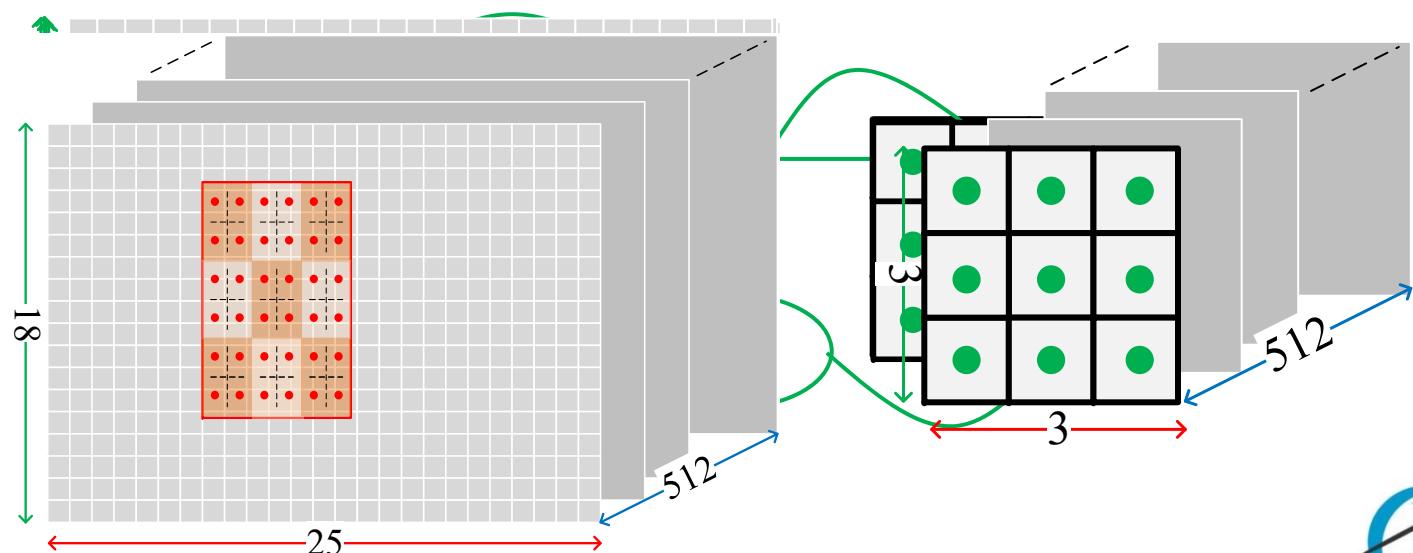
RoI Align

- Align Steps: interpolation
 - interpolate the feature value of every sampling point by **bilinear interpolation**.



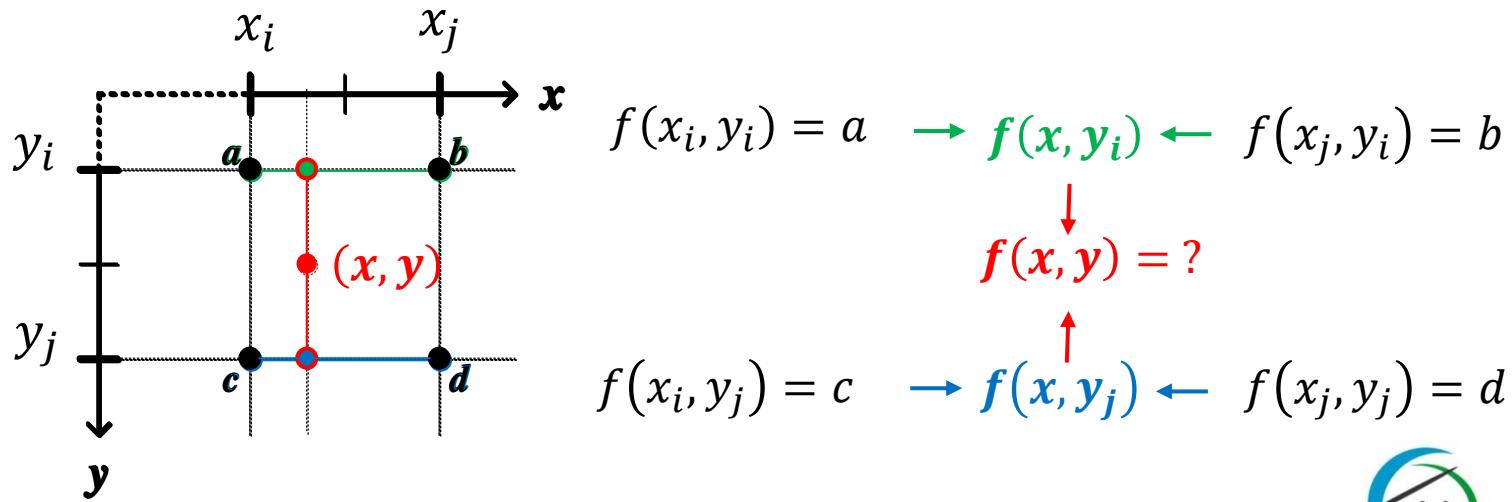
RoI Align

- Align Steps: max pooling
 - take the maximum of feature values of **sampling points** in each grid
 - aggregate the results in all channels



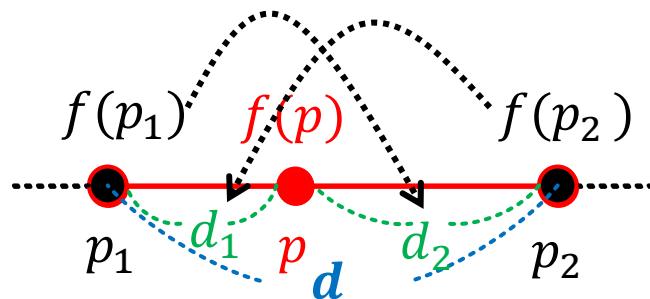
RoI Align

- Bilinear Interpolation: overview
 - It is a way to interpolate point value on a 2D grid
 - It is performed using **linear interpolation** twice, respectively, in horizontal and vertical directions



RoI Align

- Bilinear Interpolation: overview
 - Linear interpolation: interpolate the value $f(p)$ of a point p between p_1 and p_2
 - $f(p)$ is the weighted sum of $f(p_1)$ and $f(p_2)$
 - w_1 and w_2 are inversely proportional to d_1 and d_2



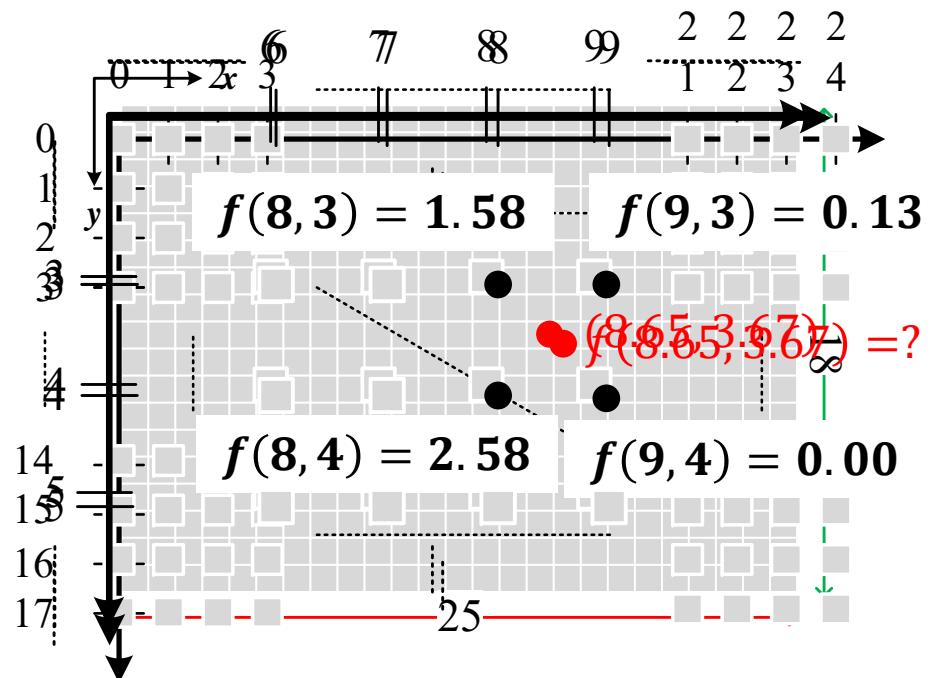
$$f(p) = \frac{d_2}{d} \times f(p_1) + \frac{d_1}{d} \times f(p_2)$$

- $w_1 + w_2 = 1.0$

- $w_1 \propto \frac{1}{d_1}$
- $w_2 \propto \frac{1}{d_2}$

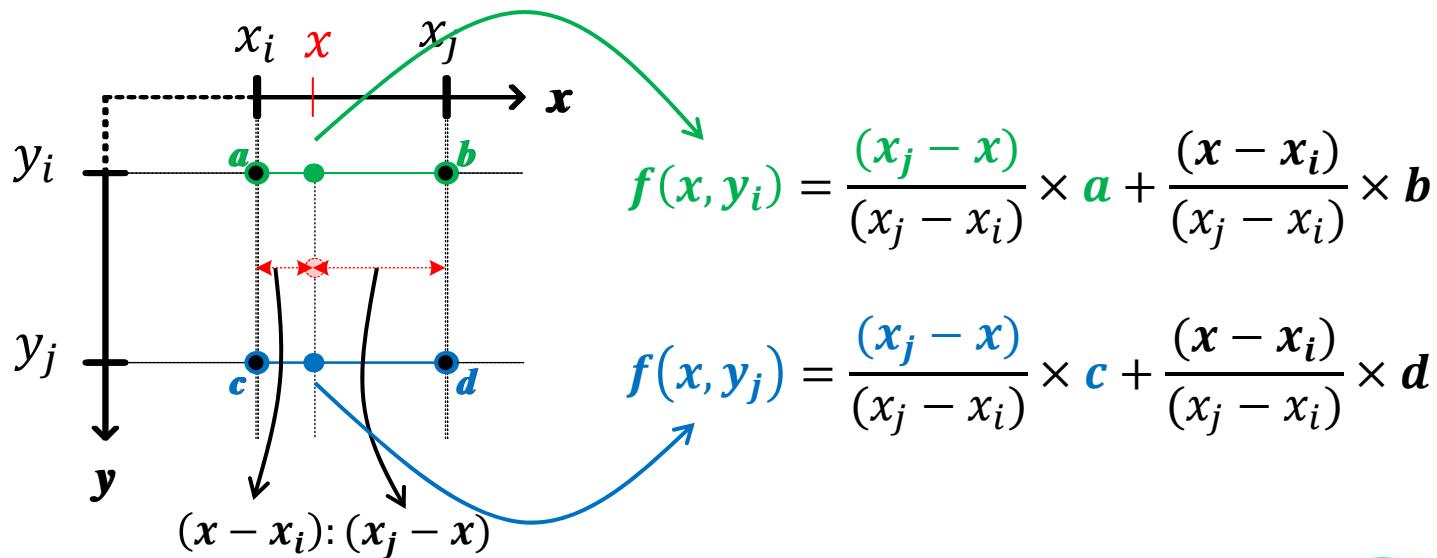
RoI Align

- Bilinear Interpolation
 - consider the conv. feature map as a square lattice of integral points
 - take the four closest integral points around the point p for interpolation



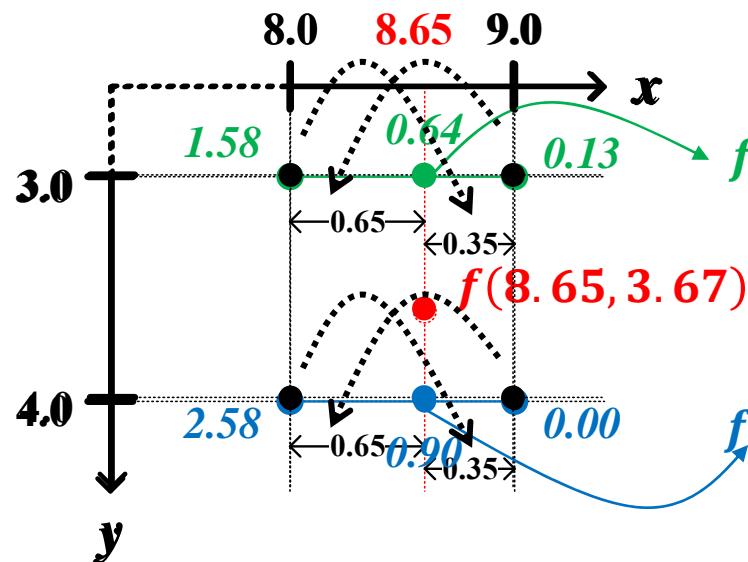
RoI Align

- Bilinear Interpolation
 - horizontal interpolation: apply linear interpolation in horizontal direction



RoI Align

- Bilinear Interpolation:
 - horizontal interpolation: apply linear interpolation in horizontal direction

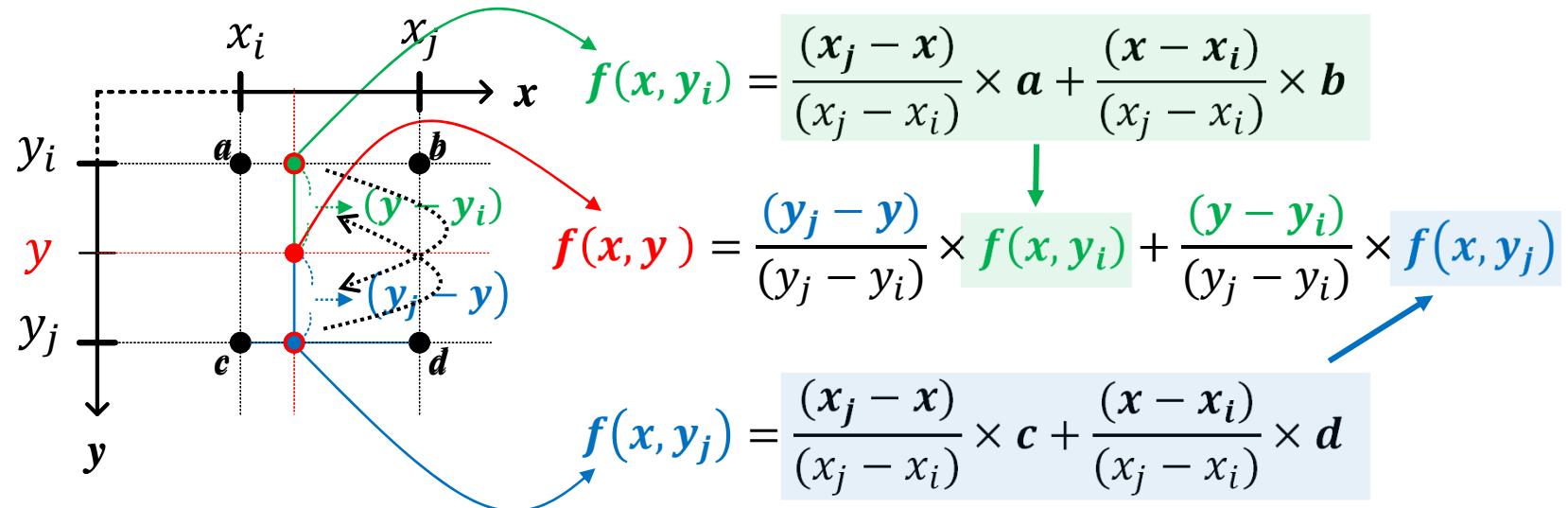


$$f(8.65, 3.0) = \frac{0.35}{1.0} \times 1.58 + \frac{0.65}{1.0} \times 0.13 = 0.64$$

$$f(8.65, 4.0) = \frac{0.35}{1.0} \times 2.58 + \frac{0.65}{1.0} \times 0.00 = 0.90$$

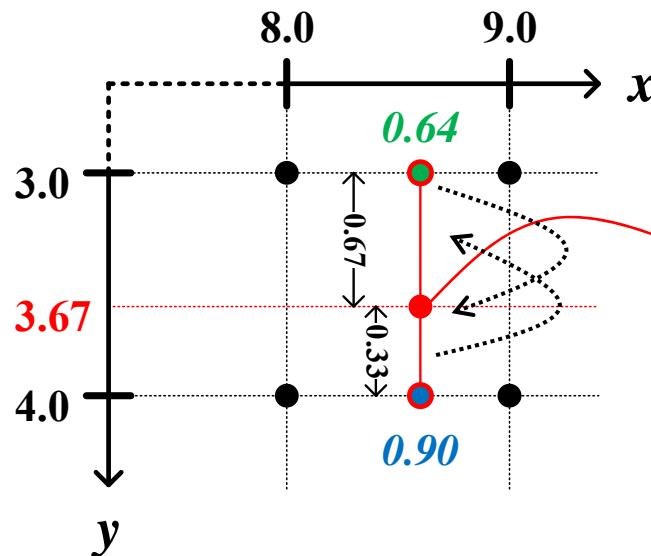
RoI Align

- Bilinear Interpolation
 - vertical interpolation: apply linear interpolation in vertical direction



RoI Align

- Bilinear Interpolation
 - vertical interpolation: apply linear interpolation in vertical direction



$$f(8.65, 3.0) = 0.64$$

$$f(8.65, 3.67) = \frac{0.33}{1.0} \times 0.64 + \frac{0.67}{1.0} \times 0.90$$

$$f(8.65, 4.0) = 0.90$$



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